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A New Framework for Efficient Shared Segment Protection Scheme for WDM Networks

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Abstract—This work introduces a new shared segment protection scheme that ensures both node and link protection in an efficient manner in terms of cost and bandwidth, while taking full advantage of the optical hop endpoints of the primary logical hops (induced by the routing) without adding extra ones for protection. As opposed to the link or path protection schemes, the segment protection scheme has been less studied although it offers an interesting compromise between those two protection schemes, attempting to encompass all their advantages. We investigate two different Shared Segment Protection (SSP) schemes: Basic Shared Segment Protection (BSSP) and Shared Segment Protection with segment Overlap (SSPO), and propose design of 100% single segment protections. In SSPO, we study the extra protection capabilities, node failure and dual link failure survivability, offered by the single 100% segment protection.

For both BSSP and SSPO schemes, we propose two novel efficient ILP formulations, based on a column generation mathematical modeling. While (SSPO) offers the advantage over (BSSP) to ensure both node and link protection, it is not necessarily much more costly. Indeed, depending on the network topology and the traffic instances, it can be shown that none of the two SSP schemes dominates the other one. Therefore, the SSPO protection scheme should be favored as it offers more protection, i.e., it adds the node protection to the link protection at the expense of a minor additional cost.

I. INTRODUCTION

Modern transport networks are based on WDM technology, where reconfigurable Optical Cross Connects (OXC) and Optical Add-Drop Multiplexers (OADM) are getting widely deployed in order to respond to the growing demand for high bandwidth services [1]. Under WDM, optical switches are equipped with optical transceivers tuned to different wavelengths and bypass capabilities in order to set up end-to-end connections - also called lightpaths - in the network. The Routing and Wavelength Assignment (RWA) problem consists thus in assigning a route in the network and a wavelength to each lightpath. This NP-hard problem has been widely studied during the last 15 years and optimal or near-optimal solutions are now available (e.g., [2]).

The Routing and Wavelength Assignment (GRWA) problem ([3], [4]) is another related problem of joint bandwidth management and routing in optical WDM networks. SONET and Optical Transport Network (ONT) are two standards that perform wavelength management by grooming finer granular-ity connections into a coarse wavelength channel.

With the event of WDM systems, hundreds of wavelengths are switched at optical nodes. This has opened up another problem of optical switching capabilities in the system. Two different switching architectures exist and are characterized by the switching domain of their signals. In the electrical switching architecture, switching nodes are equipped for each wavelength with an input and output port (transceiver) that switch the signal in the electrical domain. This architecture can support more functionalities, i.e., grooming, signal re-shaping. However, it is expensive as transceivers are the dominant cost factor. Another switching architecture is the transparent optical (photonic), where bypassing of signal is enabled through intermediate nodes along the lightpaths. This solution is further more scalable than the previous one, however, it is of limited reach, i.e., optical signal cannot travel long distance without undergoing regeneration.

In this current study, we propose a protection scheme that can span both switching architectures while taking full advantage of both of them in terms of grooming, regeneration, and switching scalability. Our protection approach is based on *Shared Segment Protection* schemes. In this context, we propose a sequential design approach where the working segments are first defined (using any given GRWA algorithm) and then the protection scheme is optimized. We therefore assume that we are given a set of working paths, where each working path is either single-hop or multi-hop, i.e., made of one or several working segments. In the present study, we limited ourselves to no more than 3 segments. It is justified by the end-to-end delay requirements, i.e., no more than two electronic/optical/electronic conversion between the source and the destination of a request. Transport blades/ports are installed at each endpoint of a working segment. This induces a natural segmentation of the lightpath that can be used as a base for the protection scheme in order to save on the network cost.

A first segment protection, called BSSP, is such that a protection is defined for each working segment, and therefore such that both working and protection segments have the same endpoints. A second segment protection, called SSPO, is such that for 3-hop working paths, we allow protection segments to encompass two working segments in order to reduce the bandwidth cost, but also and firstly to ensure node

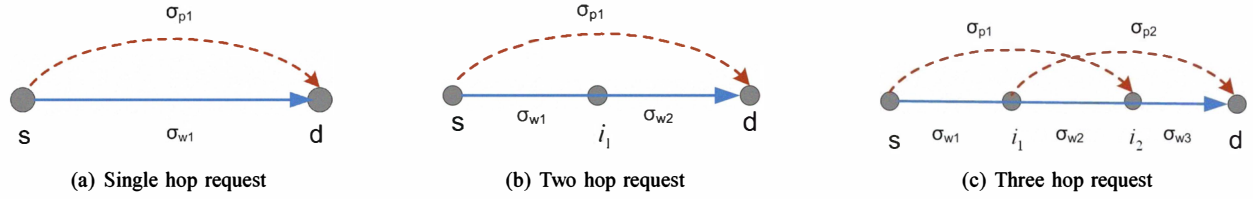


Fig. 1. SSPO protection scheme

protection. This entails some overlapping of the protection segments. In the next section, we will compare SSPO with the SLSP protection scheme of Ho and Mouftah [5] where the overlapping is at the level of the working segments. In both BSSP and SSPO, protection paths can be shared by several node and link disjoint working segments, it is illustrated in Figure 2(b) where σ_p protects two disjoint working segments.

The paper is organized as follows. In the next section, we have a qualitative comparison of the BSSP, SSPO and SLSP protection schemes. In the following sections, we investigate efficient Integer Linear Programming (ILP) models in order to design minimum cost protection schemes, in Section IV for the BSSP scheme and in Section V for the SSPO scheme. Both models rely on column generation methods which have now been shown to be extremely efficient for solving highly combinatorial problems. Computational experiences are conducted in Section VI where it is shown that SSPO offers a very attractive solution, in terms of cost and bandwidth compromises. Conclusions are drawn in the last section.

II. SHARED SEGMENT PROTECTION

A. Generalities

Although the BSSP segment protection scheme is less greedy (see Bouffard [6]) in terms of bandwidth than shared link protection, and with a nice compromise for recovery time between link and path protection, it lacks a full protection against node failures (i.e., failure of a device, as ADM, located at a node: in Figure 2(a) neither node i_1 nor i_2 are protected).

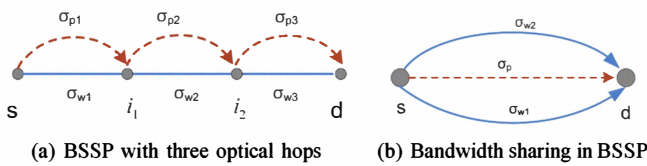


Fig. 2. BSSP protection scheme

Ho and Mouftah introduced in [5] the Short Leap Shared Protection (SLSP) scheme as an extension of BSSP, simultaneously protecting against node failure and fiber cut. Therein, the working path is subdivided into several equal length and overlapped segments, where each working segment is assigned (by the source node) a protection domain after the working path is selected. A drawback of the SLSP is the

resulting increase of the number of optical hops and the higher complexity of the signaling operations. More recent investigations of SLSP can be found in, e.g., Tapolcai *et al.* [7].

In this paper, we consider a novel segment protection scheme, called *Shared Segment Protection with Overlap* (SSPO), which, as SLSP, offers a protection against both fiber cut and node failure, while taking advantage of the segmentation induced by the routing. The SSPO scheme consists in protecting each working segment simultaneously with at least another working segment (except for single hop requests) using overlapping protection segments instead of overlapping working segments as in SLSP. All different types of protection segments in the SSPO scheme, are shown on Figure 1. Note also that a protection segment can be shared with several working segments as long as they are pairwise disjoint.

While in the present study, we will not explicitly take into account shared risk group constraints, it is worth noting that they can easily be embedded in the proposed models by modeling two working segments belonging to the same risk group as conflicting working segments.

B. BSSP vs. SSPO

Depending on the network topology and the set of working segments (that depends in turn on the set of requests and on the GRWA algorithm used to define these segments), there is no dominance of either the BSSP or the SSPO protection scheme in terms of bandwidth and port cost as evaluated through the number of transport ports. Therefore, at equal or similar cost, SSPO should be favored over BSSP as it offers a better protection scheme, i.e., node and link failure vs. link failure only.

Let us examine two examples, with quite generic patterns, and which are depicted in Figures 3 and 6.

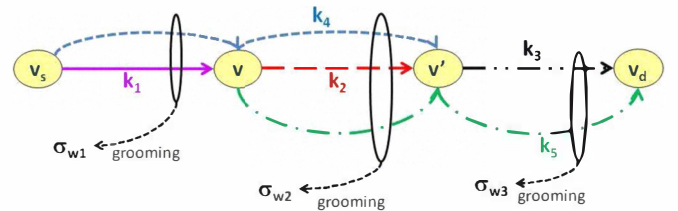


Fig. 3. Traffic Instance 1

The first traffic instance (Figure 3) is associated with a set of 5 requests, $\{k_1, k_2, k_3, k_4, k_5\}$ such that: $k_1 : v_s \mapsto v$ on

1 segment, $k_2 : v \mapsto v'$ on 2 segments, $k_3 : v' \mapsto v_d$ on one segment, $k_4 : v_s \mapsto v'$ on two segments, and $k_5 : v \mapsto v_d$ on one segment. k_1 and k_4 are groomed from v_s to v to form σ_{w1} , k_2 , k_4 and k_5 are groomed from v to v' to form σ_{w2} , k_3 and k_5 are groomed from v' to v_d to form σ_{w3} . A SSPO protection (Figure 5) requires 5 protection segments and 10 ports and is thus more expensive than a BSSP protection that uses only 3 protection segments and 6 ports as shown in Figure 4.

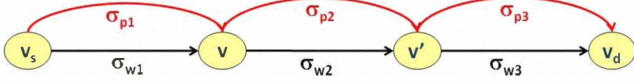


Fig. 4. BSSP: 3 Protection Segments and 6 Ports.

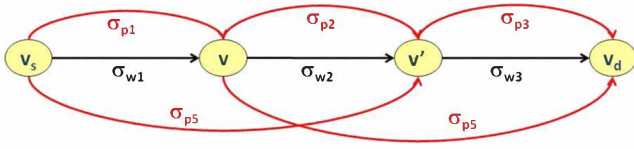


Fig. 5. SSPO: 5 Protection Segments and 10 Ports.

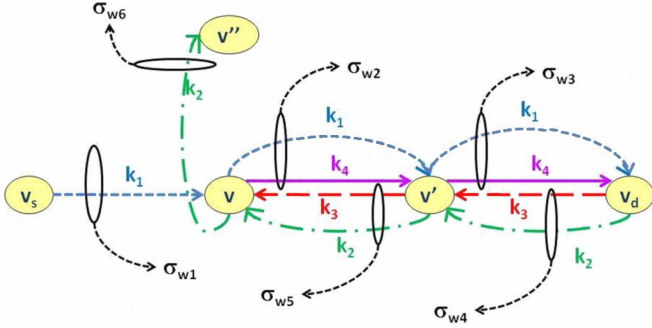


Fig. 6. Traffic Instance 2

However, there are traffic instances on which SSPO dominates BSSP. The second example, see Figure 6, is associated with a set of 4 requests, $\{k_1, k_2, k_3, k_4\}$ such that $k_1 : v_s \mapsto v_d$, $k_2 : v_d \mapsto v''$, $k_3 : v_d \mapsto v$, $k_4 : v \mapsto v_d$. Let us assume that there are routed on wavelengths using the following working segments: $\sigma_{w1} : v_s \mapsto v$, $\sigma_{w2} : v \mapsto v'$, $\sigma_{w3} : v' \mapsto v_d$, $\sigma_{w4} : v_d \mapsto v'$, $\sigma_{w5} : v' \mapsto v$, $\sigma_{w6} : v \mapsto v''$ for request k_2 . Only k_1 appears in σ_{w1} , k_2 and k_3 are groomed together on σ_{w2} and on σ_{w3} , k_1 and k_4 are groomed together on σ_{w1} and on σ_{w4} , while k_6 appears in σ_{w2} . For this example, SSPO protection is more economic than BSSP: It requires 8 ports (see Figure 8) vs. 12 ports for BSSP (see Figure 7).

Note also that depending again on the network topology and on the definition of the working segments, while it may not be possible for one of the protection scheme to define a protection for all requests (e.g. lack of available wavelengths), it may be possible for the other one, and vice-versa.

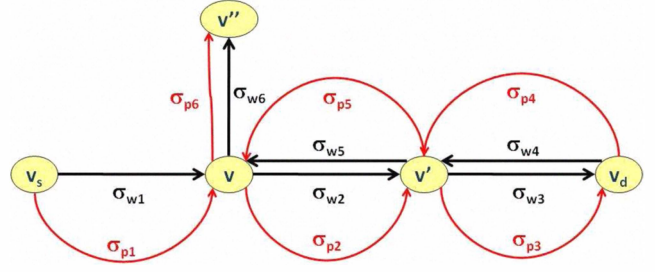


Fig. 7. BSSP: 6 Protection Segments and 12 Ports.

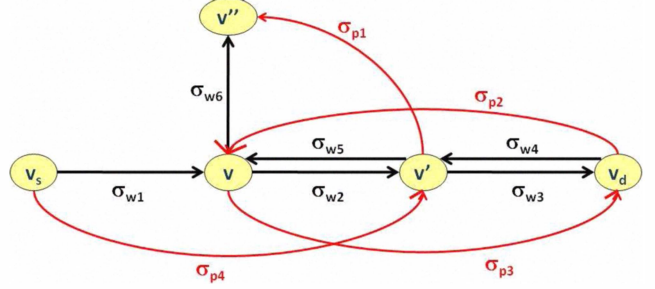


Fig. 8. SSPO: 4 protection segments and 8 Ports.

III. NOTATION AND DEFINITIONS

Consider a WDM network represented by a directed graph $G = (V, L)$ where $V = \{v_1, v_2, \dots, v_n\}$ is the set of nodes in one to one correspondence with the set of network nodes, and $L = \{\ell_1, \ell_2, \dots, \ell_m\}$ is the set of arcs, each arc being associated with a directional fiber link. Given $v \in V$, we denote by $\omega^-(v)$ and $\omega^+(v)$ the set of incoming and outgoing arcs of v respectively.

The traffic is a set K of requests such that, for each request $k \in K$, we are given its source s_k , its destination d_k , its bandwidth requirement and its working path represented by the set, S_k^W , of working segments on which its lightpath has been groomed (we assume that the request bandwidth requirement is never greater than the transport capacities of the segments). Let $S^W = \bigcup_{k \in K} S_k^W$ be the set of all working segments. Note that each (unit) working segment σ_w is characterized by a path $p(\sigma_w)$, from the source node of σ_w , denoted by $v_s(\sigma_w)$, to its destination node $v_d(\sigma_w)$ and a wavelength $\lambda(\sigma_w)$. It follows that each working segment σ_w is associated with all requests groomed from $v_s(\sigma_w)$ to $v_d(\sigma_w)$ on wavelength $\lambda(\sigma_w)$ along path $p(\sigma_w)$.

Let K^i be the set of requests with a working path using i segments, $i = 1, 2, 3$.

Denote by S_w^P the set of suitable protection segments for a working segment σ_w , in the context of the BSSP scheme, and by $S_{w,k}^P$, the set of suitable protection segments for a working segment σ_w and a request k that is routed on it, in the context of the SSPO scheme. Let $S^P = \bigcup_{\sigma_w \in S^W} S_w^P$ or $S^P = \bigcup_{\sigma_w \in S^W} S_{w,k}^P$ be the set of protection segments/paths according to the selected protection schemes.

Two protection segments are in conflict if they use the same

wavelength on a given fiber link. Two working segments can be protected by two conflicting protection segments if and only if they do not share any fiber link. For SSPO protection, we add the condition that they do not share any node except for their endpoints. Indeed, if a fiber link shared by two working segments is cut, we need to reroute each pair of working segments on two different alternative paths. We use the following parameters:

$$\delta_{ww'} = \begin{cases} 1 & \text{if } \sigma_w \text{ and } \sigma_{w'} \text{ can be protected by the same} \\ & \text{protection segment} \\ 0 & \text{otherwise,} \end{cases}$$

for all pair $\{w, w'\}$ of working segments. Note that $\delta_{ww'} = \delta_{w'w}$.

IV. BSSP PROTECTION SCHEME

In this section, we will restrict our attention to the BSSP protection. We propose to investigate a column generation formulation in order to find an optimal BSSP protection design. We will outline the main features and advantages of column generation formulations in the next paragraph, and then detail the proposed model in the following paragraphs. For the reader who is not familiar with column generation formulations and solutions, see, e.g., Chvatal [8] and Barnhart *et al.* [9].

A. BSSP Protection Configurations

Before setting the BSSP column generation model, denoted by CG-BSSP, we need to introduce the so-called *wavelength BSSP protection configurations*. For each wavelength λ , we define a *wavelength BSSP protection configuration*, as a set of protection segments all routed on λ , which protect a given set of working segments that are not necessarily routed on wavelength λ . In order to reduce the number of configurations to be explored, we only consider the maximal ones, i.e., those that are not embedded in larger ones with identical cost.

A column generation model leads to a decomposition where the master problem takes care of selecting the best configurations, one for each wavelength, i.e., the set of configurations that minimizes the cost as evaluated by the number of transport ports. The pricing problem identifies, dynamically and one at a time, the most promising configurations, i.e., the configurations with a negative reduced cost (i.e., the objective of the pricing, see [8] if not familiar with linear programming tools). The pricing problem therefore handles the constraints associated with the definition of a protection segment, i.e., no link sharing between a working segment and its protection, protection sharing whenever it helps to reduce the cost. Note that due the efficiency of column generation, only a very small number of configurations will indeed need to be generated. Indeed, as soon as we cannot find any new configuration with a negative reduced cost, i.e., any new configuration that allows reduction of the master objective value, we can claim we have reach the optimal solution of the linear relaxation of the master problem. Then, one can use either rounding off techniques or

ILP solver to deduce an integer solution, see Barnhart *et al.* [9] for more details.

B. CG-BSSP Master Problem

Each variable z_c of the master problem is associated with a configuration $c \in \mathcal{C}^\lambda$ for a given wavelength λ : $z_c = 1$ if the c configuration, $c \in \mathcal{C}^\lambda$, is selected on wavelength λ , and 0 otherwise. We denote by B^c the unit cost of a configuration, $c \in \mathcal{C}$, which, in the present study, will be equal to the number of required ports (whether input or output ports), i.e.,

$$B^c = \sum_{v \in V} (B_v^{c, \text{IN}} + B_v^{c, \text{OUT}}),$$

where $B_v^{c, \text{IN}}$ and $B_v^{c, \text{OUT}}$ are the number of input and output ports at node v , respectively.

Let $\mathcal{C}^{\text{BSSP}}$, or \mathcal{C} for short when there is no confusion, be the overall set of potential wavelength BSSP protection configurations. Although it is a huge set following its definition, in practice only a small number of its elements (e.g., few hundred for large network and traffic instances) will need to be listed in order to get an optimal or a near optimal solution. Let a^C be the column of the constraint matrix associated with the decision variable z_C . Each working segment is associated with a component of a^C : $a_{\sigma_w}^C = 1$ if σ_w can be protected under this configuration, and 0 otherwise. We then get the following mathematical model for the master problem:

$$\min \sum_{\lambda \in \Lambda} \sum_{c \in \mathcal{C}^\lambda} B^c z_c$$

subject to:

$$\sum_{c \in \mathcal{C}^\lambda} z_c \leq 1 \quad \lambda \in \Lambda \quad (1)$$

$$\sum_{\lambda \in \Lambda} \sum_{c \in \mathcal{C}^\lambda} a_{\sigma_w}^c z_c \geq 1 \quad \sigma_w \in \mathcal{S}^W \quad (2)$$

$$z_c \in \{0, 1\} \quad c \in \mathcal{C}. \quad (3)$$

Constraints (1) express that we must select at most one configuration per wavelength. Constraints (2) express the condition that each working segment must be protected at least once. Note that, in some cases, due to the search for maximal wavelength protection configurations, we may end up with "over" protection of some working segments: Not only it does not affect the port cost, but we could argue that in case of higher order failure, it might be useful.

C. CG-BSSP Pricing Problems

There are as many pricing problems as the number of wavelengths in order to take into account the wavelengths already assigned to the working segments. Consider the auxiliary graph $G_\lambda = (V, L_\lambda)$ where $L_\lambda = \{e \in L : (e, \lambda) \notin \sigma_w \text{ for } \sigma_w \in \mathcal{S}^W\}$. In order to define protection segments, we use a flow modeling formulation where each segment σ_p that protects a given working segment σ_w is associated with a unit flow from $v_s(\sigma_w)$ to $v_d(\sigma_w)$ where $v_s(\sigma_w)$ and $v_d(\sigma_w)$ denotes respectively the source and the destination nodes of the σ_w segment. We therefore introduce flow variables $\varphi_{e\lambda}^{\sigma_w}$

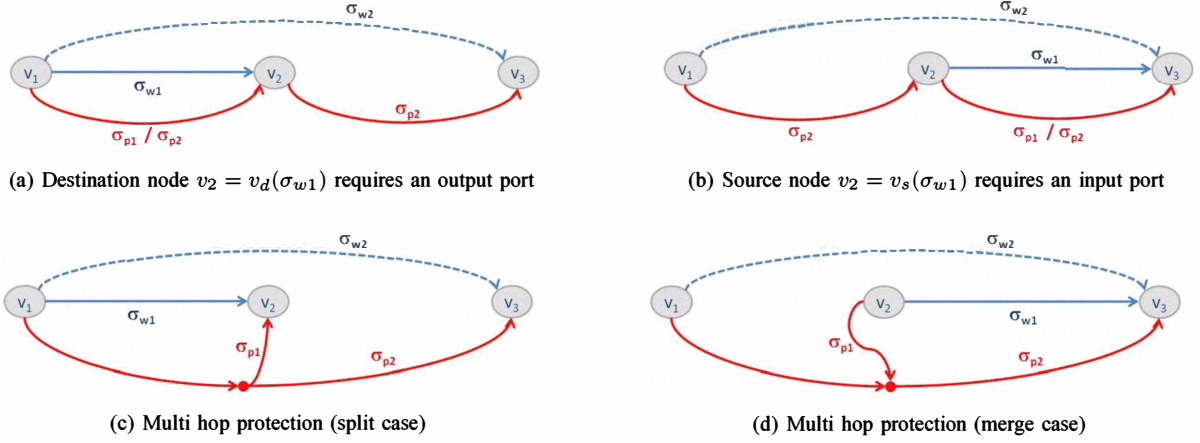


Fig. 9. Multi pop protection schemes assuming $\delta_{w1,w2} = 1$

such that $\varphi_{e\lambda}^{\sigma_w} = 1$ if e supports a segment with wavelength λ in order to protect σ_w , and 0 otherwise. Note that in case of a protection segment σ_p shared by two link disjoint working segments σ_w and σ'_w with the same endpoints v_s and v_d , there will be an overall flow of value 2 (i.e., $\varphi_{e\lambda}^{\sigma_w} + \varphi_{e\lambda}^{\sigma'_w}$) from v_s to v_d on all links e of σ_p . Let us now study the mathematical formulation of the pricing problem for a given wavelength λ .

1) *Objective Function:* The objective function of a given pricing problem corresponds to the minimization of the reduced cost (see, e.g., [8] if not familiar with linear programming tools) that is defined by:

$$\bar{B}^c = B^c + u_0^\lambda - u \cdot a^c = B^c + u_0^\lambda - \sum_{\sigma_w \in \mathcal{S}^W} u_{\sigma_w} a_{\sigma_w}^c$$

for $c \in C^\lambda$, where $a_{\sigma_w}^c = \sum_{e \in \omega^+(v_s(\sigma_w))} \varphi_e^{\sigma_w}$, and u_0^λ and $u = (u_{\sigma_w})_{\sigma_w \in \mathcal{S}^W}$ are the dual variables associated respectively with constraints (1- λ) and (2- σ_w) of the master problem.

As $B^c = \sum_{v \in V} (B_v^{c,IN} + B_v^{c,OUT})$, we first need to compute the number of input ($B_v^{c,IN}$) and output ($B_v^{c,OUT}$) ports at node v . They can be evaluated as follows:

$$B_v^{c,OUT} \geq \sum_{e \in \omega^+(v)} \psi_e^{OUT} \quad v \in V \quad (4)$$

$$B_v^{c,IN} \geq \sum_{e \in \omega^-(v)} \psi_e^{IN} \quad v \in V, \quad (5)$$

$$\psi_e^{IN}, \psi_e^{OUT} \in \{0, 1\} \quad e \in L_\lambda \quad (6)$$

where ψ_e^{OUT} and ψ_e^{IN} are decision variables, indicating whether or not an output/input port is required on link e .

In order to alleviate the notations, we now get ride of the λ index until this end of this section and simply denote the flow variables by $\varphi_e^{\sigma_w}$. For the same reason, we will also omit the c index.

Flow variables ψ_e^{OUT} and ψ_e^{IN} must satisfy:

$$\psi_e^{IN} \geq \varphi_e^{\sigma_w} \quad e \in \omega^-(v_d(\sigma_w)), \sigma_w \in \mathcal{S}^W \quad (7)$$

$$\psi_e^{OUT} \geq \varphi_e^{\sigma_w} \quad e \in \omega^+(v_s(\sigma_w)), \sigma_w \in \mathcal{S}^W \quad (8)$$

$$\alpha_v^{OUT} \geq \varphi_e^{\sigma_w} \quad v \in V : v = v_d(\sigma_w), \quad e \in \omega^-(v), \sigma_w \in \mathcal{S}^W \quad (9)$$

$$\psi_e^{OUT} \geq \varphi_e^{\sigma_w} + \alpha_v^{OUT} - 1 \quad v \in V : v = v_d(\sigma_w), \quad e \in \omega^+(v), \sigma_w \in \mathcal{S}^W \quad (10)$$

$$\alpha_v^{IN} \geq \varphi_e^{\sigma_w} \quad v \in V : v = v_s(\sigma_w), \quad e \in \omega^+(v), \sigma_w \in \mathcal{S}^W \quad (11)$$

$$\psi_e^{IN} \geq \varphi_e^{\sigma_w} + \alpha_v^{IN} - 1 \quad v \in V : v = v_s(\sigma_w), \quad e \in \omega^-(v), \sigma_w \in \mathcal{S}^W \quad (12)$$

$$\alpha_v^{OUT}, \alpha_v^{IN} \in \{0, 1\} \quad v \in V \quad (13)$$

Constraints (7) (resp. (8)) expresses that:

$$\begin{aligned} \psi_e^{IN} &= \max_{\sigma_w \in \mathcal{S}^W} \varphi_e^{\sigma_w} & e \in \omega^-(v_d(\sigma_w)), \sigma_w \in \mathcal{S}^W \\ \psi_e^{OUT} &= \max_{\sigma_w \in \mathcal{S}^W} \varphi_e^{\sigma_w} & e \in \omega^+(v_d(\sigma_w)), \sigma_w \in \mathcal{S}^W. \end{aligned}$$

In other words, $\psi_e^{IN} = 1$ (resp. $\psi_e^{OUT} = 1$) as soon as link $e \in \omega^-(v_d(\sigma_w))$ (resp. $e \in \omega^+(v_d(\sigma_w))$) for $\sigma_w \in \mathcal{S}^W$ supports at least one protection flow.

Constraints (9) and (10) take care of the case illustrated in Figure 9(a) where a segment protection is reused as the first hop of another segment protection (in which case $\alpha_v^{OUT} = 1$ for $v = v_2 = v_d(\sigma_{w1})$ for the example of Figure 9(a)). Constraints (11) and (12) are similar constraints for the cases illustrated in Figure 9(b).

In order to detect the multi-hop protection schemes as illustrated in Figures 9(c) and 9(d), for all $v \in V$ such that v is not the endpoint of a protected working segment in the current configuration, we need the following constraints:

$$\begin{aligned} \sum_{\sigma_w \in S} \max_{e \in \omega^-(v)} \varphi_e^{\sigma_w} - \sum_{\sigma_w \in S} \max_{e \in \omega^+(v)} \varphi_e^{\sigma_w} &\leq |S| \alpha_v \quad S \subseteq \mathcal{S}^W \\ \sum_{\sigma_w \in S} \max_{e \in \omega^+(v)} \varphi_e^{\sigma_w} - \sum_{\sigma_w \in S} \max_{e \in \omega^-(v)} \varphi_e^{\sigma_w} &\leq |S| \alpha_v \quad S \subseteq \mathcal{S}^W \\ \psi_e^{IN} &\geq \varphi_e^{\sigma_w} + \alpha_v - 1 & e \in \omega^-(v), \sigma_w \in S \\ \psi_e^{OUT} &\geq \varphi_e^{\sigma_w} + \alpha_v - 1 & e \in \omega^+(v), \sigma_w \in S \\ \alpha_v &\in \{0, 1\} & v \in V, \end{aligned}$$

where all working segments of S are pairwise independent, i.e., $\delta_{ww'} = 1$ for any $w, w' \in S$.

The above constraints are highly costly to include in the mathematical model, taking into account the very few multi-hop protection occurrences as illustrated in 9(c) and 9(d). We therefore decided not to include them but only check a posteriori their occurrences.

a) *Constraints*: Constraints of the pricing problem deal with the constraints associated with the definition of a proper wavelength protection configuration, they are as follows:

$$\sum_{e \in \omega^-(v)} \varphi_e^{\sigma_w} = \sum_{e \in \omega^+(v)} \varphi_e^{\sigma_w} \quad \sigma_w \in \mathcal{S}^W, \quad v \in V : v \notin \{v_s(\sigma_w), v_d(\sigma_w)\} \quad (14)$$

$$\sum_{e \in \omega^+(v_s(\sigma_w))} \varphi_e^{\sigma_w} = \sum_{e \in \omega^-(v_d(\sigma_w))} \varphi_e^{\sigma_w} \leq 1 \quad \sigma_w \in \mathcal{S}^W \quad (15)$$

$$\sum_{e \in \omega^-(v_s(\sigma_w))} \varphi_e^{\sigma_w} = \sum_{e \in \omega^+(v_d(\sigma_w))} \varphi_e^{\sigma_w} = 0 \quad \sigma_w \in \mathcal{S}^W \quad (16)$$

$$\varphi_e^{\sigma_w} + \varphi_e^{\sigma_{w'}} \leq 1 + \delta_{ww'} \quad e \in L_\lambda; \sigma_w, \sigma_{w'} \in \mathcal{S}^W \quad (17)$$

$$\varphi_e^{\sigma_w} \in \{0, 1\} \quad e \in L_\lambda, e \notin \sigma_w, \sigma_w \in \mathcal{S}^W \quad (18)$$

$$\varphi_e^{\sigma_w} = 0 \quad e \in (L \setminus L_\lambda) \cup \sigma_w, \sigma_w \in \mathcal{S}^W \quad (19)$$

Constraints (14) correspond to the flow conservation at intermediate nodes. Constraints (15) expresses that the flow starting at $v_s(\sigma_w)$ finishes at $v_d(\sigma_w)$ while (16) means that no flow arrives at $v_s(\sigma_w)$ and none leaves from $v_d(\sigma_w)$. Constraints (17) prevents two working segments in conflict (i.e., they share at least one fiber link) to be protected by the same protection segment. Equation (19) prevents a given link to be used both in a working segment and in its protection. Moreover, it forbids to use link e with the λ wavelength assignment in the definition of σ_p if (e, λ) is already included in a working segment.

V. SSPO PROTECTION SCHEME

In this section, we focus on the novel SSPO protection scheme with overlapping protection segments as described in Section II.

A. The CG-SSPO Column Generation Model with Wavelength Configuration

1) *Master problem*: The master problem has a similar mathematical expression than for the BSSP protection scheme, except the definition of the the wavelength protection configurations. In this case, *wavelength SSPO protection configurations* refers to the set of (λ) protection segments that are shared by their protected working counterpart. The main difference between the BSSP and SSPO lies in the definition of the protection segments. For single hop working paths, they are the same as in BSSP: Their endpoints coincide with those of the working segment, while they cannot share any link of the working segments they protect. For 2-hop working paths, an SSPO protection is made of a single protection segment which has its two endpoints in common with those of the working path. For 3-hop working paths, an SSPO protection

is either made of a single protection path (no difference with path protection) or of two protection segments that overlap over the second working segments, i.e., if the working path of request k is made of three segments $(\sigma_w, \sigma'_w, \sigma''_w)$, the first protection segment may start at $v_s(\sigma_w)$ and end at $v_d(\sigma'_w)$, while the second protection segment would start at $v_s(\sigma'_w)$ and end at $v_d(\sigma''_w)$. Notice that in both 2-hop and 3-hop working paths the working segment σ'_w is automatically protected if the others are. It is why we do not have to add specific constraints for them.

The SSPO protection, working segments of different requests can be either protected by overlapping segments in case of 3-hop working paths, or sequential non overlapping segments, see Figure 5. In this case, the protection segments and the working segments do not necessarily share the same endpoints. Constraints (20) are added in the master problem in order to protect different working segments, by overlapping or sequential segments, of different connections:

$$\sum_{\lambda \in \Lambda} \sum_{C_\lambda \in \mathcal{C}} a_{\sigma_w, k}^{C_\lambda} z_{C_\lambda} \geq 1 \quad k \in K, \sigma_w \in \mathcal{S}^k \quad (20)$$

2) Pricing Problem:

a) *Objective*: Minimize the reduced cost of the master:

$$\bar{B}_{C_\lambda} = B_{C_\lambda} - \sum_{k \in K} \sum_{\sigma_w \in \mathcal{S}^k} u_{\sigma_w, k} a_{\sigma_w, k}^{C_\lambda} + u_0^\lambda \quad (21)$$

where $u_{\sigma_w, k}$ is the dual variable associated with constraint (20- (k, σ_w)).

For 1 hop:

$$a_{\sigma_w, k}^{C_\lambda} = \sum_{e \in \omega^+(v_s(\sigma_w))} \varphi_e^{\sigma_w, k}$$

where $v_s(\sigma_w) = v_s^k$.

For 2 hops:

$$a_{\sigma_w, k}^{C_\lambda} = \sum_{e \in \omega^+(v_s(\sigma_w))} \varphi_e^{\sigma_w, k} \quad \text{if } v_s(\sigma_w) = v_s^k$$

$$a_{\sigma_w, k}^{C_\lambda} = \sum_{e \in \omega^-(v_d(\sigma_w))} \varphi_e^{\sigma_w, k} \quad \text{if } v_d(\sigma_w) = v_d^k.$$

For 3 hops $(\sigma_w, \sigma'_w, \sigma''_w)$:

$$a_{\sigma_w, k}^{C_\lambda} = \sum_{e \in \omega^+(v_s(\sigma_w))} \varphi_e^{\sigma_w, k} \quad \text{if } v_s(\sigma_w) = v_s^k$$

$$a_{\sigma'_w, k}^{C_\lambda} = a_{\sigma''_w, k}^{C_\lambda}$$

$$a_{\sigma_w, k}^{C_\lambda} = \sum_{e \in \omega^-(v_d(\sigma_w))} \varphi_e^{\sigma_w, k} \quad \text{if } v_d(\sigma_w) = v_d^k.$$

Let $\mathcal{S}^W = \mathcal{S}^{W_1} \cup \mathcal{S}^{W_2} \cup \mathcal{S}^{W_3}$, where $\mathcal{S}^{W_i} = \cup_{k \in K^i} (\mathcal{S}^W \cap \mathcal{S}_k^W)$ is the set of working segments of requests with i working segments (i.e., hops), $i = 1, 2, 3$ and \mathcal{S}_k^W is the set of working segments for request k . Denote by v_s^k and v_d^k respectively the source and the destination node of the working path of request k .

The number of output and input ports at node v can be evaluated as in CG-BSSP with constraints (4), (5) and (6)

using the flow variables ψ_e^{OUT} and ψ_e^{IN} . Those last variables must satisfy the same constraints as in the CG-BSSP model for single hop working paths. At intermediate nodes of protection segments, previous constraints (10)-(12) also apply. Single hop requests:

$$\psi_e^{\text{OUT}} \geq \varphi_e^{\sigma_w, k} \quad e \in \omega^+(v_s(\sigma_w)), k \in K_1 \quad (22)$$

$$\psi_e^{\text{IN}} \geq \varphi_e^{\sigma_w, k} \quad e \in \omega^-(v_d(\sigma_w)), k \in K_1 \quad (23)$$

Two hop requests:

$$\psi_e^{\text{OUT}} \geq \varphi_e^{\sigma_w, k} \quad e \in \omega^+(v_s(\sigma_w)), k \in K_2 \quad (24)$$

$$\psi_e^{\text{IN}} \geq \varphi_e^{\sigma_w', k} \quad e \in \omega^-(v_d(\sigma_w')), k \in K_2 \quad (25)$$

Three hop requests:

$$\psi_e^{\text{OUT}} \geq \varphi_e^{\sigma_w, k} \quad e \in \omega^+(v_s(\sigma_w)), k \in K_3 \quad (26)$$

$$\psi_e^{\text{IN}} \geq \varphi_e^{\sigma_w'', k} \quad e \in \omega^-(v_d(\sigma_w'')), k \in K_3 \quad (27)$$

$$\psi_e^{\text{OUT}} \geq \varphi_e^{\sigma_w', k} \quad e \in \omega^+(v_s(\sigma_w')), k \in K_3 \quad (28)$$

$$\psi_e^{\text{IN}} \geq \varphi_e^{\sigma_w', k} \quad e \in \omega^-(v_d(\sigma_w')), k \in K_3 \quad (29)$$

b) *Constraints:* As in the previous model, the protection segment associated with a working segment will be defined by a unit flow following the SSPO protection scheme. We therefore need to specify the connection index together with the working segment to be protected as there might be different protection segments associated with a given working segment depending on the requests. Though the previous flow conservation constraints are also adapted and used in SSPO (they are not illustrated in SSPO because of space limitation).

$$\sum_{e \in \omega^+(v_s(\sigma_w))} \varphi_e^{\sigma_w, k} = \sum_{e \in \omega^-(v_d(\sigma_w))} \varphi_e^{\sigma_w, k} \leq 1 \quad \sigma_w \in K^1 \quad (30)$$

Constraints (30) are used in single hop protection to set up the protection flow at the source and destination of protection segments.

$$\sum_{e \in \omega^+(v_s(\sigma_w))} \varphi_e^{\sigma_w, k} = \sum_{e \in \omega^-(v_d(\sigma_w'))} \varphi_e^{\sigma_w, k} \leq 1 \quad (31)$$

$$\sum_{e \in \omega^-(v_d(\sigma_w))} \varphi_e^{\sigma_w, k} = \sum_{e \in \omega^+(v_s(\sigma_w'))} \varphi_e^{\sigma_w, k} = 0 \quad (32)$$

for all $v_s(\sigma_w) = v_s^k, \{\sigma_w, \sigma_w'\} = S_k^W, k \in K^2$.

Constraints (31)-(32) are used to set up the protection flows and source and destination of 2-hop protection segments.

Similarly, for 3-hop working paths, constraints (33) express that the protection segment starts at $v_s(\sigma_w)$ and ends at either $v_d(\sigma_w')$ or $v_d(\sigma_w'')$, where σ_w' is the second working segment and σ_w'' the third.

$$\begin{aligned} \sum_{e \in \omega^-(v_d(\sigma_w'))} \varphi_e^{\sigma_w, k} + \sum_{e \in \omega^-(v_d(\sigma_w''))} \varphi_e^{\sigma_w, k} \\ \geq \sum_{e \in \omega^+(v_s(\sigma_w))} \varphi_e^{\sigma_w, k} \\ v_s(\sigma_w) = v_s^k, v_d(\sigma_w'') = v_d^k, (\sigma_w, \sigma_w', \sigma_w'') = S_k^W, k \in K^3 \end{aligned} \quad (33)$$

Constraints (34) applies for the third working segment σ_w'' , expressing that the protection segment starts at either $v_s(\sigma_w)$ or $v_s(\sigma_w')$ and ends at $v_d(\sigma_w'')$.

$$\begin{aligned} \sum_{e \in \omega^+(v_s(\sigma_w))} \varphi_e^{\sigma_w, k} + \sum_{e \in \omega^+(v_s(\sigma_w'))} \varphi_e^{\sigma_w, k} \\ \geq \sum_{e \in \omega^-(v_d(\sigma_w''))} \varphi_e^{\sigma_w, k} \\ v_s(\sigma_w) = v_s^k, v_d(\sigma_w'') = v_d^k, (\sigma_w, \sigma_w', \sigma_w'') = S_k^W, k \in K^3 \end{aligned} \quad (34)$$

We do not need constraints for defining a protection for the second working segment of a 3-hop request, as its is protected by the same protection segment than the first or the last working segment.

VI. COMPUTATIONAL RESULTS

In this section we compare the performance of SSPO to BSSP. We consider in the performance evaluation two network topologies NSF [10] and COST239 [11] networks, and traffic distributions groomed following the approach in [6]. In the adopted traffic model, a working connection can span either (1, 2 or 3)-hop segments. The traffic load and distribution over the three type of connections are given in Table I under the header "Overall number of" and "Number of", respectively.

Both BSSP and SSPO optimization models are implemented and solved with the help of a (integer) linear programming solver (CPLEX package, [12]).

In NSF network (relatively sparse), the overlapping of protection segments depends on the distribution of the connections over the (1, 2, and 3)-hop working segment classes. This factor (overlapping protection segments), which is illustrated in column 5 under the header "Overlapping protection segments", achieves its lower bound 75% when the number of 3-hop and 2-hop working segments are equal (see first row of Table I), and its highest bound 100% when the number of 2-hop connection is very low compared to 3-hop connections, see row 4. For all other cases where the number of 2-hop connections is higher than 3-hop, the number of overlapping protection segments is also high. In COST 239, more connected network compared to NSF, the number of overlapping protection segments is very high and clearly not highly dependent on the distribution of connections over the number of hops. It is in [94%, 100%] of the total number of protection segments.

In column 6 and 7, we propose a comparison of the port cost between the two protection models. The cost of SSPO in terms of number of ports depend on the number of overlapping segments. In NSF, when compared to BSSP, which does not depend on the overlapping of segment, we see that they achieve comparable performance (comparable cost) when the number of 2-hop and 3-hop connections are comparable (first 3 lines), lower cost when 2-hop is lower (row 4), and almost higher cost whenever the number of 2-hop connection is high. In COST 239, this trend is not observed. The distribution of the traffic over the 2-hop and 3-hop connections does not

TABLE I
COMPARISON OF BSSP AND SSPO PERFORMANCES

	Overall number of requests	Number of			Overlapping segments (%)	Port cost		Node protection (%)		Dual link protection (%)	
		3-hop requests	2-hop requests	single-hop requests		BSSP	SSPO	BSSP	SSPO	BSSP	SSPO
NSF	32	12	12	8	75	38	42	53.3	100	36.4	65.2
	89	33	46	10	90	63	66	0.0	100	0.0	42.6
	94	41	47	6	83	64	60	0.0	100	0.0	38.6
	100	89	8	3	100	66	58	22.2	100	9.5	15.2
	166	48	85	33	88	84	75	5.6	100	6.7	49.1
	181	48	85	48	94	58	73	17.7	100	21.1	54.9
	241	70	102	69	89	94	78	12.7	100	14.8	53.2
	324	114	161	49	90	72	79	38.9	100	31.5	56.7
	354	114	183	57	84	58	76	4.8	100	6.4	46.8
COST 239	546	206	262	78	99	60	78	42.3	100	33.6	57.0
	47	13	17	17	94	56	42	13.6	100	9.4	55.7
	99	27	50	22	98	44	48	6.9	100	6.5	50.5
	106	35	54	17	100	45	45	6.4	100	13.3	47.0
	170	91	54	25	100	60	56	9.6	100	7.1	40.3
	174	48	81	45	100	53	68	26.0	100	23.4	57.0
	204	59	94	51	100	37	50	24.3	100	22.2	55.9

clearly affect the node cost in this case. This is mainly due to the high connectivity of COST 239 network. Though, richer connectivity in the protection capacity setup.

In terms of node protection, we observe that SSPO guarantees 100% protection against any single node failure even when the protection segment are not 100% overlapping. In this case, as the objective is to minimize the required protection capacity to provide 100% single segment protection, the protection segments tend to be paths. Though, also provide 100% protection against node failures. A very poor node protection is achieved by BSSP. This performance can be explained by the protection segments mainly made each of one fiber link.

Similarly for dual link failure protection, SSPO clearly outperforms BSSP, and usually offers more than 50% of dual link failure protection. The dual link failure protection in SSPO is at its lowest level when the number of 2-hop connections is far lower than the number of 3-hop connections (rows 4), its highest level when they are equal (row 1), and an in-between level in all other cases. Because of the rich connectivity, survivability to dual link failures is higher in the COST 239 network than the NSF in SSPO, but it is not sensitive to the distribution of (2, 3)-hop connections.

VII. CONCLUSION

In this paper we investigated a new shared segment protection scheme, SSPO, which ensures both node and link protection and compare it with the classical BSSP scheme. While both depends on the grooming results, i.e., the definition of the working segments, SSPO has a stronger dependency on the overlapping of the protection segments. Results show that with a small extra cost, SSPO offers an extended range of protection capabilities including node and dual-link failure protection. However, further investigations are needed in order to find out if the additional cost could be reduced thanks to a more efficient and adapted traffic grooming in order to reduce the number of overlapping segments.

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